

Peetre's Theorem

On a C^∞ manifold, one can define the notion of a differential operator on C^∞ -functions by appealing to the natural definition on open subsets of \mathbb{R}^n and using local coordinates to give this meaning on the manifold. While such a definition is useful for calculations, it seems a bit clumsy and inelegant. The theorem by Peetre proven below gives a simple characterization of differential operators on manifolds without appealing to local coordinates. The proof below is adapted from the proof in [He84, pp. 233–239] which itself is adapted from the proof given in [Na68, pp. 171–176]. We begin with some standard notation and propositions before coming to the main course of Peetre's Theorem.

Notation and Basic Propositions

Let $V \subset \mathbb{R}^n$ be open. Denote by $C_c^\infty(V)$ the set of functions compactly supported inside V . Let ∂_i denote the partial derivative with respect to the i -th coordinate in \mathbb{R}^n , and for a multi-index $\alpha = (\alpha_1, \dots, \alpha_n)$ of non-negative integers we put

$$D^\alpha = \partial_1^{\alpha_1} \cdots \partial_n^{\alpha_n} \quad , \quad x^\alpha = x_1^{\alpha_1} \cdots x_n^{\alpha_n}$$
$$|\alpha| = \alpha_1 + \cdots + \alpha_n \quad , \quad \alpha! = \alpha_1! \cdots \alpha_n!$$

In addition, if $\beta \leq \alpha$ (i.e. $\beta_i \leq \alpha_i$ for every i) then we can also define

$$\alpha - \beta = (\alpha_1 - \beta_1, \dots, \alpha_n - \beta_n)$$
$$\binom{\alpha}{\beta} = \frac{\alpha!}{\beta!(\alpha - \beta)!}$$

With this very convenient notation, the generalized Leibniz rule for the differentiation of two (sufficiently differentiable) functions f and g can be written as

$$D^\alpha(fg) = \sum_{\mu+\nu=\alpha} \binom{\alpha}{\mu} D^\mu(f)D^\nu(g).$$

For any subset $S \subset V$ and $m \in \mathbb{Z}_{\geq 0}$ we define

$$\|f\|_m^S = \sum_{|\alpha| \leq m} \sup_{x \in S} |(D^\alpha f)(x)|.$$

When $S = V$ we will drop the superscript. Clearly, these form a countable family of semi-norms on $C^\infty(V)$.

Proposition 1. *Let $C \subset U \subset V$ where U and V are open and C a closed subset of \mathbb{R}^n . Then there is a function $\phi \in C^\infty(V)$ such that $\phi \equiv 1$ on C , $\phi \equiv 0$ on $V \setminus U$, and $0 \leq \phi \leq 1$ everywhere on V .*

Proposition 2. *Let $C \subset \mathbb{R}^n$ be any closed subset. Then there exists a $\phi \in C^\infty(\mathbb{R}^n)$ such that*

$$C = \{x \in \mathbb{R}^n : \phi(x) = 0\}.$$

For the construction of such functions, see [Sp05, pp.32–32] and [He84, pp.234–235].

Lemma 1. *Let $m > 0$, and suppose $f \in C^\infty(\mathbb{R}^n)$ has all derivatives of order less than or equal to m vanish at the origin. Then given $\epsilon > 0$ there exists a $g \in C^\infty(\mathbb{R}^n)$ vanishing in a neighborhood of the origin and satisfying*

$$\|g - f\|_m < \epsilon.$$

Proof: Let $\phi \in C^\infty(\mathbb{R}^n)$ be such that $\phi(x) = 0$ for $|x| \leq \frac{1}{2}$, $\phi(x) = 1$ for $|x| \geq 1$, and $0 \leq \phi \leq 1$ everywhere. For $\delta > 0$ define

$$g_\delta(x) = \phi\left(\frac{x}{\delta}\right) f(x).$$

Note that $g_\delta \equiv 0$ on $|x| \leq \frac{\delta}{2}$ and $g_\delta \equiv f$ on $|x| \geq \delta$. Hence, the theorem will follow if we can show that for each multi-index $|\alpha| \leq m$

$$\sup_{|x| \leq \delta} |D^\alpha g_\delta(x) - D^\alpha f(x)| \rightarrow 0 \text{ as } \delta \rightarrow 0.$$

By the assumption that f and its derivatives up to order m vanish at the origin, we know that

$$\sup_{|x| \leq \delta} |D^\alpha f(x)| \rightarrow 0 \text{ as } \delta \rightarrow 0.$$

Using the Leibniz rule and the chain rule shows that

$$D^\alpha g_\delta(x) = \sum_{\mu+\nu=\alpha} \binom{\alpha}{\mu} \delta^{-|\mu|} (D^\mu \phi)\left(\frac{x}{\delta}\right) (D^\nu f)(x).$$

Since ϕ is a fixed function, bounded in absolute value by 1, and constant outside a compact set (so that all of its derivatives have compact support),

we can get an upper bound on $(D^\mu \phi)(x)$. Thus, we can conclude that there is a constant C_1 so that

$$|D^\alpha g_\delta(x)| \leq C_1 \sum_{\mu+\nu=\alpha} \delta^{-|\mu|} |(D^\nu f)(x)|.$$

But $D^\nu f$ is such that all of its derivatives up to order $m - |\nu|$ vanish at the origin. So, expanding $D^\nu f$ about the origin, we can show that

$$\sup_{|x| \leq \delta} |D^\nu f(x)| \leq C_2 \delta^{m+1-|\nu|}.$$

Hence, we conclude that

$$\sup_{|x| \leq \delta} |D^\alpha g_\delta(x)| \leq C_1 C_2 \sum_{\mu+\nu=\alpha} \delta^{m+1-|\nu|-|\mu|}.$$

Since $|\nu| + |\mu| = |\alpha| \leq m$ we see that

$$\sup_{|x| \leq \delta} |D^\alpha g_\delta(x)| \rightarrow 0 \text{ as } \delta \rightarrow 0. \square$$

Corollary. *The lemma above holds if the origin is replaced by any point $y \in \mathbb{R}^n$.*

Peetre's Theorem on \mathbb{R}^n

Definition. *Let $V \subset \mathbb{R}^n$ be an open set. A differential operator on V is a linear mapping $L : C_c^\infty(V) \rightarrow C_c^\infty(V)$ such that for each open set U compactly contained in V there exists a finite family of functions $a_\alpha \in C^\infty(U)$ so that*

$$L\phi = \sum_{\alpha} a_\alpha D^\alpha \phi$$

for every $\phi \in C_c^\infty(U)$.

Proposition 3. *Let L be a differential operator on V , then we have*

$$\text{supp}(L\psi) \subset \text{supp}(\psi) \text{ for all } \psi \in C_c^\infty(V). \quad (\dagger)$$

Peetre's Theorem proves the amazing result that (\dagger) is also *sufficient* for a linear operator on $C_c^\infty(V)$ to be a differential operator! We first establish this on \mathbb{R}^n and then extend the result to smooth manifolds.

Lemma 2. *Suppose ψ_1 and ψ_2 in $C_c^\infty(V)$ agree on some neighborhood of $x \in V$ and the linear operator L satisfies (\dagger) , then $L\psi_1(x) = L\psi_2(x)$.*

Proof: Clearly $x \notin \text{supp}(\psi_1 - \psi_2)$. So, by assumption $x \notin \text{supp}(L(\psi_1 - \psi_2))$ and so $L\psi_1(x) = L\psi_2(x)$ by linearity of L . \square

Corollary. *If L is a linear operator defined on $C_c^\infty(V)$ satisfying (\dagger) , then L can be extended to all of $C^\infty(V)$.*

Proof: Let ϕ_x be any element of $C_c^\infty(V)$ that is identically 1 on a neighborhood of x . For any $f \in C^\infty(V)$ define

$$Lf(x) = L(\phi_x(x) \cdot f(x)).$$

By the lemma above, the particular choice of ϕ_x is irrelevant. \square

The next two lemmas are the main technical results that facilitate the proof of the theorem.

Lemma 3. *Suppose $L : C_c^\infty(V) \rightarrow C_c^\infty(V)$ is linear and satisfies (\dagger) . Then every $a \in V$ has an open neighborhood U compactly contained in V together with a non-negative integer m and a positive constant C so that*

$$\|Lu\|_0 \leq C\|u\|_m \text{ for all } u \in C_c^\infty(U \setminus \{a\}).$$

Proof: Suppose this were false for some $a \in V$. Let $U_0 \subset V$ be an open neighborhood of a that is compactly contained in V . Then by assumption, there must be a function $u_1 \in C_c^\infty(U_0 \setminus \{a\})$ such that $\|Lu_1\|_0 > 2^2\|u_1\|_1$.

Let $U_1 = \{x : u_1(x) \neq 0\}$. Then $U_0 \setminus \bar{U}_1$ is an open neighborhood of a . Again by our assumption, there must be a $u_2 \in C_c^\infty(U_0 \setminus (\bar{U}_1 \cup \{a\}))$ such that $\|Lu_2\|_0 > 2^4\|u_2\|_2$. Continue this process by induction to get a sequence of open sets U_1, U_2, \dots with

$$\bar{U}_k \subset U_0 \setminus \{a\}$$

$$\bar{U}_k \cap \bar{U}_l = \emptyset \text{ for } k \neq l$$

and a sequence of functions $u_k \in C_c^\infty(U_0 \setminus (\bar{U}_1 \cup \dots \cup \bar{U}_{k-1} \cup \{a\})) \subset C_c^\infty(V)$ satisfying

$$\begin{aligned} U_k &= \{x : u_k(x) \neq 0\} \\ \|Lu_k\|_0 &> 2^{2k}\|u_k\|_k. \end{aligned}$$

Now define

$$u(x) = \sum_{i=1}^{\infty} \frac{2^{-k}}{\|u_i\|_i} u_i(x).$$

It is easy to show that this is a well-defined element of C_c^∞ . Moreover, by construction

$$u|_{U_k} = 2^{-k}\|u_k\|^{-1}u_k$$

which by linearity and our support condition (\dagger) implies that

$$Lu|_{U_k} = 2^{-k}\|u_k\|^{-1}Lu_k.$$

Since $\|Lu_k\|_0 > 2^{2k}\|u_k\|_k$, there must be $x_k \in U_k$ so that $Lu(x_k) > 2^k$. Hence, Lu is unbounded which is impossible since $Lu \in C_c^\infty(V)$ by assumption. \square

Lemma 4. *Suppose $L : C_c^\infty(V) \rightarrow C_c^\infty(V)$ is linear and satisfies (\dagger). Let $U \subset V$ be any open set, and assume there is a constant $C > 0$ and a non-negative integer m so that*

$$\|Lu\|_0 \leq C\|u\|_m \text{ for all } u \in C_c^\infty(U).$$

Then there are functions $a_\alpha \in C^\infty(V)$ such that

$$(Lu)(x) = \sum_{|\alpha| \leq m} a_\alpha(x)(D^\alpha u)(x)$$

for all $x \in U$ and $u \in C_c^\infty(U)$.

Proof: By the corollary to Lemma 2, we can extend L to all of $C^\infty(V)$. For each $a \in V$ and each multi-index α , define

$$\begin{aligned} Q_{\alpha,a}(x) &= (x_1 - a_1)^{\alpha_1} \dots (x_n - a_n)^{\alpha_n} \\ b_\alpha(a) &= (LQ_{\alpha,a})(a). \end{aligned}$$

Clearly, the functions b_α belong to $C^\infty(V)$. For any $u \in C_c^\infty(U)$ and $a \in U$, consider the function $f_{a,m}$ defined by

$$f_{a,m} = u - \sum_{|\alpha| \leq m} \frac{(D^\alpha u)(a)}{\alpha!} Q_{\alpha,a} \quad (1)$$

(note that $f_{a,m}$ is just the difference between u and its Taylor Polynomial of order m centered at a). By construction, $f_{a,m}$ has all derivatives of order $|\alpha| \leq m$ vanishing at a . By the proof of Lemma 1, we can approximate $f_{a,m}$ in the semi-norm $\|\cdot\|_m$ by functions g_ν which exactly equal $f_{a,m}$ outside some neighborhood of a but vanish identically near a . By (†) and the corollary to Lemma 2, we must have Lg_ν vanish identically near a for all ν . Thus, by our assumption

$$\|L(f_{a,m} - g_\nu)\|_0 \leq \|f_{a,m} - g_\nu\|_m \rightarrow 0 \text{ as } \nu \rightarrow \infty$$

and so

$$(Lf_{a,m})(a) = \lim_{\nu \rightarrow \infty} (Lg_\nu)(a) = 0.$$

Applying L to both sides of (1) and using $(Lf_{a,m})(a) = 0$ gives

$$(Lu)(a) = \sum_{|\alpha| \leq m} \frac{(LQ_{\alpha,a})(a)}{\alpha!} (D^\alpha u)(a).$$

Taking $a_\alpha(x) = \frac{b_\alpha(x)}{\alpha!}$ we get the desired result. \square

We finally have all the necessary technical elements to prove

Theorem 1 (Peetre's Theorem). *Suppose $L : C_c^\infty(V) \rightarrow C_c^\infty(V)$ is linear and satisfies $\text{supp}(L\psi) \subset \text{supp}(\psi)$ for all $\psi \in C_c^\infty(V)$. Then L is a differential operator.*

Proof: Let $U \subset V$ be open with \bar{U} compact and $\bar{U} \subset V$. Applying Lemma 3 to every point of \bar{U} gives us an open cover. By the compactness of \bar{U} we get a finite cover of open sets U_1, \dots, U_r neighborhoods of points a_1, \dots, a_r in \bar{U} , respectively; by the construction in the lemma, we can take each \bar{U}_i to be compact. For each i , we know that there are constants $C_i > 0$ and positive integers m_i so that $\|Lu\|_0 \leq C_i \|u\|_{m_i}$ for every $u \in C_c^\infty(U_i \setminus \{a_i\})$. Set $C = \max\{C_i\}$ and $m = \max\{m_i\}$. Then we have

$$\|Lu\|_0 \leq C \|u\|_m \tag{2}$$

for each i and every $u \in C_c^\infty(U_i \setminus \{a_i\})$. Let $1 = \sum_{i=1}^{r+1} \phi_i$ be a C^∞ -partition-of-unity subordinate to the covering $U_1, \dots, U_r, V \setminus \bar{U}$ of V (c.f. [Sp05, pp. 51 – 52]).

Let $u \in C_c^\infty(U \setminus \{a_1, \dots, a_r\})$, then we can write $u = \sum_{i=1}^{r+1} \phi_i u$ and (2) holds for each $\phi_i u$. Hence, we have

$$\|Lu\|_0 = \left\| \sum_{i=1}^r L(\phi_i u) \right\|_0 \leq \sum_{i=1}^r \|L(\phi_i u)\|_0 \leq C \sum_{i=1}^r \|\phi_i u\|_m.$$

Using the Leibniz rule to expand the derivatives of $\phi_i u$ and realizing that the ϕ_i are fixed functions of compact support allows us to conclude that for any $u \in C_c^\infty(U \setminus \{a_1, \dots, a_r\})$

$$\|Lu\|_0 \leq C' \|u\|_m$$

for some (possibly different) fixed constant C' .

By Lemma 4, we can conclude that

$$(Lu)(x) = \sum_{|\alpha| \leq m} a_\alpha(x) (D^\alpha u)(x)$$

for all $x \in U \setminus \{a_1, \dots, a_r\}$ and some collection of functions $a_\alpha \in C^\infty(V)$. But, both sides are continuous! Hence they must be equal on all of U . \square

Peetre's Theorem and Differential Operators on Manifolds

As is typical, we can use the local result in \mathbb{R}^n to prove a similar result on smooth manifolds. To that end, we formulate the following (non-standard) definition.

Definition. Let M be a C^∞ -manifold. A differential operator on M is a linear operator $L : C_c^\infty(M) \rightarrow C_c^\infty(M)$ satisfying $\text{supp}(L\psi) \subset \text{supp}(\psi)$ for all $\psi \in C_c^\infty(M)$

The great advantage of this formulation is that it makes no reference to local coordinates. We now show that this definition is justified.

Theorem 2. The definition above is equivalent to the usual definition of differential operators on manifolds.

Proof: Let (U, ϕ) be a chart on M . Consider the mapping $L^\phi : C_c^\infty(\phi(U)) \rightarrow C_c^\infty(\phi(U))$ given by

$$L^\phi F = (L(F \circ \phi)) \circ \phi^{-1}.$$

An easy check shows that this satisfies the hypotheses of Peetre's Theorem. Hence, for any open set compactly contained in $\phi(U)$ we have

$$(L^\phi F)(x) = \sum_{\alpha} a_{\alpha}(x)(D^{\alpha}F)(x).$$

Thus, setting $F = f \circ \phi^{-1}$ where $f \in C_c^{\infty}(U)$ and $y = \phi^{-1}(x) \in U$ gives

$$Lf(y) = \sum_{\alpha} a_{\alpha}(\phi(y))(D^{\alpha}(f \circ \phi^{-1}))(\phi(y))$$

for every open W compactly contained in U . This is just the usual definition of a differential operator on a smooth manifold. That the usual definition implies our (non-standard) definition is trivial! \square

References

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